
In-class Exercises for Chapter 4

Discussed in class on Thursday, week 2

Topics: Optimization

Problem 1: Solution Existence for Univariate Concave Functions

Consider a univariate, real-valued function $f : (\underline{x}, \bar{x}) \mapsto \mathbb{R}$, $\underline{x}, \bar{x} \in \mathbb{R}$ so that $\underline{x} < \bar{x}$. Suppose that

(i) f is once differentiable,

(ii) f is concave, and that

(iii) there exist $a, b, c \in (\underline{x}, \bar{x})$ with $a < b < c$ so that $f(a) < f(c) < f(b)$.

Can you argue that f assumes a global maximum on (\underline{x}, \bar{x}) ?

Hint 1. Recall that concavity is a desirable feature in unconstrained maximization.

Hint 2. Think about combining the Mean Value and Intermediate Value Theorem.

Problem 2: Unconstr. Optimization and Matrix Definiteness (online)

In the exercises of Chapter 3, we investigated definiteness of the second derivative of $x'Ax$ for

$A = \begin{pmatrix} 1 & \alpha \\ \beta & 4 \end{pmatrix}$. Recall that the second derivative was $A + A'$ and that for $v \in \mathbb{R}^2$,

$$v'(A + A')v = 2(v_1^2 + (\alpha + \beta)v_1v_2 + 4v_2^2)$$

(i) Can you use an optimization problem approach to find the values for α and β where $A + A'$ is not positive semi-definite, i.e. where there exist $v \in \mathbb{R}^2$ for which $v'(A + A')v < 0$?

To help you with the solution, note that if we write $v = \lambda v_0$, we have

$$v'(A + A')v = 2\lambda^2(v_{0,1}^2 + (\alpha + \beta)v_{0,1}v_{0,2} + 4v_{0,2}^2)$$

Hence, the magnitude does not matter for the property of being strictly negative, and you can reduce the search for v with $v'(A + A')v < 0$ to a direction vector. Because the magnitude of the direction vector does not matter and as if $v_1 = 0$, then the expression is weakly positive, there is no loss in setting $v_{0,1} = 1$ and restricting the search to the value $v_{0,2}$ that yields $v'(A + A')v < 0$.

Problem 3: Saving Time in Optimization

Solve

$$\max \frac{4}{3}x^2 + y + xz \quad \text{s.t.} \quad \|(x, y, z)\|_2 \leq 1$$

where $\|\cdot\|_2$ is the Euclidean norm of the \mathbb{R}^3 .

You will get a multitude solutions to the FOC. For any one of these, using the second order condition, you would have to check two determinants of the Bordered Hessian, one for a 3×3 and one for a 4×4 matrix. What may help to avoid this is that you can make an argument for solution existence, and also the Lagrangian multiplier condition.

Three simplifications and intuitions can be extremely helpful:

- If $\|(x, y, z)\|_2 < 1$, we can increase the objective varying marginally y .
- By norm non-negativity, $\|(x, y, z)\|_2 \leq 1$ is equivalent to $\|(x, y, z)\|_2^2 \leq 1^2$.
- Closed balls of the \mathbb{R}^n are compact.